# Invariant star-products on symplectic manifolds 

M. DE WILDE, P.B.A. LECOMTE, D. MELOTTE<br>Université de Liège, Institut de Mathématique Avenue des Tilleuls, 15, B-4000 Liège (Belgium)


#### Abstract

Let $(M, F)$ be a symplectic manifold and consider a Lie subalgebra $\mathbb{G}$ of its Lie algebra of symplectic vector fields. We prove that every one-differentiable deformation of order $k$ of the Poisson Lie algebra of $M$, which is invariant with respect to $\mathbb{G}$, extends to an invariant one-differentiable deformation of infinite order. If $M$ admits a $\mathbb{G}$-invariant linear connection, a similar result holds true for differentiable deformations and for star-products. In particular, if $M$ admits $a \mathrm{G}$ --invariant linear connection, there always exists $a \mathbb{G}$-invariant star-product.


## INTRODUCTION

Let $M$ be a smooth connected Hausdorff second countable manifold equipped with a symplectic form $F$. We assume that $\operatorname{dim} M>2$. Denote by L the Lie algebra of symplectic vector fields of $(M, F)$.

Let $\mathbb{G}$ be a Lie subalgebra of $\mathbf{L}$. The aim of this paper is to study the formal deformations of the Poisson Lie algebra ( $N, P$ ) where $N$ is the space of all smooth real functions on $M$ and $P$ the Poisson bracket, and the star-products which are invariant by $\mathbb{G}$.

This problems has already been considered by various authors, namely $[6,5,1]$. It is shown in [6] that, if there exists an invariant Vey star-product, then $M$ admits an invariant symplectic connection. We prove here that the existence of an invariant linear connection implies that every invariant formal deformation of $P$ or star-product of finite order extends to an invariant formal deformation of

[^0]$P$ or star-product (of infinite order).
It is proved in [6], § 18, that, for the Hochschild cohomology of $N$, an invariant coboundary is the coboundary of an invariant cochain. However, using then an argument of the Neroslavsky-Vlassov type [8] leads to obstructions lying in the third invariant de Rham cohomology space of $M$. In this note, we avoid these obstructions essentially by adapting to the invariant case the proof of [2] of the existence of star-products on an arbitrary symplectic manifold. To do this, we need the description of the invariant Chevalley cohomology of ( $N, P$ ) obtained in [3]. The adaptation is straightforward in the case of 1 -differentiable deformations but more delicate in the general case.

We use the definitions and notations of [2].

## THE MAP $\boldsymbol{\tau}$

Recall that $A_{\text {diff, } n c}^{p}(N)$ is the space of differential cochains on $N$ (i.e. alternating $(p+1)$-linear maps of $N^{p+1}$ into $\left.N\right)$, vanishing on the constants ( $n c$ ); $A_{\text {diff }}^{p}(\mathcal{H}(M)$, $N$ ) is the space of differential $N$-valued $(p+1)$-cochains on the Lie algebra of all vector fields $\mathcal{H}(M)$.

Then $\mu^{*}: A_{\text {diff }}^{p}(\mathcal{H}(M), N) \rightarrow A_{\text {diff, } n c}^{p}(N)$ is defined by

$$
\mu^{*} c\left(u_{0}, \ldots, u_{p}\right)=c\left(H_{u_{0}}, \ldots, H_{u_{p}}\right)
$$

where $H_{u}$ is the Hamiltonian vector field of $u$.
One of the keys in [2] is the existence of a right inverse $\tau$ of $\mu^{*}$ for $p=1$, with appropriate additional properties. One more is required here: that $\tau$ preserves invariance.

Denote by $\partial$ and $\partial^{\prime}$ the Chevalley coboundary operators of $A_{\text {diff }}(N)$ and $A_{\text {diff }}(\mathscr{H}(M), N)$ and by $S_{\Gamma}^{3}$ and $\phi_{\Gamma}$ the Vey cocycle of $A_{\text {diff }, n c}^{1}(N)$ and the cocycle of $A_{\text {diff }}^{1}\left(\mathscr{H}(M), \Lambda^{2}(M)\right)$ such that $S_{\Gamma}^{3}=\mu^{*}\left\langle\Lambda, \phi_{\Gamma}\right\rangle$, where $\Lambda$ is the contravariant analogue of $F$.

PROPOSITION 1. Let $M$ admit a $\mathbb{G}$-invariant connection $\Gamma$. Then there exists a linear map $\tau: A_{\text {diff, } n c}^{1}(N) \rightarrow A_{\text {diff }}^{1}(\mathcal{H C}(M), N)$ such that

$$
\begin{equation*}
\mu^{*} \circ \tau=\operatorname{id} \text { on } A_{\mathrm{diff}, n c}^{1}(N) \tag{i}
\end{equation*}
$$

$$
\begin{equation*}
\tau \circ \mu^{*}=\text { id on } \Lambda^{2}(M) \tag{ii}
\end{equation*}
$$

$$
\begin{equation*}
\tau\left(f S_{\Gamma}^{3}\right)=f\left\langle\Lambda, \phi_{\Gamma}\right\rangle, \quad \forall f \in N \tag{iii}
\end{equation*}
$$

$$
\begin{equation*}
(\tau \circ \partial) A_{\mathrm{diff}, n c}^{0}(N) \subset \mathrm{im} \partial^{\prime} \tag{iv}
\end{equation*}
$$

$$
\begin{equation*}
\text { if } C \in A_{\text {diff }, n c}^{1}(N) \text { is } \mathbb{G} \text {-invariant, } \tau C \text { is } \mathbb{G} \text {-invariant. } \tag{v}
\end{equation*}
$$

It is known [6] that each $C \in A_{\text {diff, } n c}^{1}(N)$ can be written (in a unique way)

$$
C(u, v)=\sum_{p, q}\left\langle T^{p, q}, \nabla^{p} u \otimes \nabla^{q} v\right\rangle
$$

where $T^{p, q}$ is a contravariant $(p+q)$-tensor, symmetric in its first $p$ and its last $q$ arguments and where $\langle$,$\rangle indicates the contraction of the first p$ indices of $T^{p, q}$ with $\nabla^{p} u$ and of the last one's with $\nabla^{q} v$; since $\nabla$, the covariant derivative corresponding to $\Gamma$, is invariant, $C$ is invariant if and only if each $T^{p, q}$ is invariant. Thus $\tau^{\prime} C$, obtained from $C$ by replacing

$$
\nabla^{p} u=\nabla^{p-1} \mathrm{~d} u=\nabla^{p-1} i\left(H_{u}\right) F
$$

by

$$
X \rightarrow \nabla^{p-1} i(X) F
$$

transforms an invariant element of $A_{\text {diff, } n c}^{1}(N)$ into an invariant element of $A_{\text {diff }, n c}^{1}(N)$, and $\tau^{\prime}$ is a right inverse of $\mu^{*}$. Unfortunately, it does not verify (iii) and (iv). Clearly, $\tau^{\prime}$ can be defined similarly on each $A_{\text {diff, } n c}^{p}(N)$.

Denote by $I$ the subspace of all invariant elements of $A_{\text {diff, } n c}^{1}(N)$ and set

$$
A_{\mathrm{diff}, n c}^{1}(N)=\left[\partial A_{\mathrm{diff}, n c}^{0}(N)+I+\mu^{*} \Lambda^{2}(M)+N \cdot S_{\Gamma}^{3}\right] \oiint E_{1}
$$

We can write

$$
\partial A_{\mathrm{diff}, n c}^{0}(N)+I+\mu^{*} \Lambda^{2}(M)+N \cdot S_{\Gamma}^{3}=\mu^{*} \Lambda^{2}(M) \oplus N \cdot S_{\Gamma}^{3} \oplus E_{2} \oplus E_{3} \oplus E_{4}
$$

where $E_{2} \subset I \cap \operatorname{im} \partial, E_{3} \subset \operatorname{im} \partial \backslash I, E_{4} \subset I \backslash i m \partial$.
We now define $\tau$ as follows:
(i) on $E_{1}, \tau$ is any right inverse of $\mu^{*}$,
(ii) on $E_{4}, \tau=\tau^{\prime}$,
(iii) on $E_{3}, \tau$ is defined as in [2],
(iv) on $\mu^{*} \Lambda^{2}(M), \tau \circ \mu^{*} \Omega=\Omega$,
(v) on $N S_{\Gamma}^{3}, \tau\left(f S_{\Gamma}^{3}\right)=f\left\langle\Lambda, \phi_{\Gamma}\right\rangle$,
(vi) on $E_{2}$ : according to [3], prop. 7.1., if $C=\partial D \in A_{\text {diff, } n c}^{1}(N)$ is invariant, $C=\partial\left(E+\mu^{*} \omega\right)$, where $E$ is invariant and $\omega \in \Lambda^{1}(M)$. There exist thus $k_{1}: E_{2} \rightarrow A_{\text {diff }, n c}^{0}(N)$ and $k_{2}: E_{2} \rightarrow \Lambda^{1}(M)$ such that $k_{1} E_{2}$ is made of invariant elements and $\partial \circ\left(k_{1}+\mu^{*} \circ k_{2}\right)=$ id on $E_{2}$. Set $\tau=\partial^{\prime} \circ \tau^{\prime} \circ k_{1}+\partial^{\prime} \circ k_{2}$.
Then $\tau$ verifies all the required properties.

## THE ONE-DIFFERENTIABLE CASE

Recall that a formal differential deformation of order $k$ of $P$ is a formal series
$\mathcal{L}_{\nu}=\sum_{i=0}^{\infty} \nu^{i} C_{i}$ of differential bilinear maps $C_{i}: N \times N \rightarrow N$, vanishing on the constants and such that the formal Jacobi identity is verified up to the order $k$. In other words, [, ] denoting the Nijenhuis-Richardson bracket, the components of $\nu^{i}(i \leqslant k)$ in $\left[\mathcal{L}_{\nu}, \mathcal{L}_{\nu}\right]$ are vanishing.

The first result in [2] essentially shows the following. If $\mathcal{L}_{\nu}$ is a differential deformation of $P$ and if $\Omega$ is closed, the differential deformation of order $k$ $\mathcal{L}_{\nu}+\nu^{k} \mu^{*} \Omega$ extends to a differential deformation. The same holds true within the class of invariant deformations. The results of [2] are stated for local deformations but apply trivially to differential deformations.

THEOREM 2. Assume that $M$ admits a $\mathbb{G}$-invariant linear connection. Let $\mathcal{L}_{\nu}$ be a differential $\mathbb{G}$-invariant deformation of $P$ and let $\Omega$ be a closed $\mathbb{G}$-invariant 2-form. Define inductively $\mathbb{L}_{\nu}^{k}(k \in \mathbb{N})$ by $\mathbb{L}_{\nu}^{0}=\mathcal{L}_{\nu}$ and

$$
\left.\ell \mathbb{L}_{\nu}^{\ell}\right|_{U}=\left.\sum_{p+q=\ell-1}\left[\mathbb{L}_{\nu}^{p}, \mu^{*} i(X) \tau \mathbb{L}_{\nu}^{q}\right]\right|_{U}
$$

whenever $\Omega=\operatorname{di}(X) F$ on the open subset $U$ of $M$. Then each $\mathbb{L}_{\nu}^{k}$ is globally defined, $\mathbb{G}$-invariant, and

$$
\sum_{k=0}^{\infty} \mu^{k} \mathbb{L}_{v}^{k}
$$

is a differential deformation in $\mu$ of $\mathcal{L}_{\nu^{\prime}}$ In particular,

$$
\sum_{k=0}^{\infty} \nu^{k t} \mathrm{IL}_{\nu}^{k}
$$

is $a \mathbb{G}$-invariant deformation of Pequal to $\mathcal{L}_{\nu}+\nu^{t} \mu^{*} \Omega$ at the order $t$.
The only point added to thm. 2.1. in [2] is the $\mathbb{G}$-invariance. We prove it by induction on $\ell$. Since $\Omega$ is invariant, for $Y \in \mathbb{G}$, on the open subset $U$,

$$
0=L_{Y} \Omega=L_{Y} \operatorname{di}(X) F=\operatorname{di}\left(L_{Y} X\right) F=L_{L_{Y} X} F .
$$

Thus $L_{Y} X \in \mathrm{~L}$. Assume now that $\mathbb{L}_{\nu}^{p}$ is $\mathbb{G}$-invariant for $p<\ell$. Then, since $\mathbb{I L}_{\nu}^{q}$ and $\tau \mathbb{L}{ }_{\nu}^{q}$ are invariant, if $U$ is contractible and $L_{Y} X=H_{u}$ on $U$,

$$
\begin{aligned}
\left.\ell L_{Y} \mathbb{L}_{\nu}^{\ell}\right|_{U} & =\sum_{p+q=\ell-1}\left[\mathbb{L}_{\nu}^{p}, \mu^{*} i\left(L_{Y} X\right) \tau \mathbb{L}_{\nu}^{q}\right]= \\
& =\frac{1}{2} i(u) \sum_{p+q=\ell-1}\left[\mathbb{L}_{\nu}^{p}, \mathbb{L}_{\nu}^{q}\right]=0
\end{aligned}
$$

since $\Sigma \mu^{k} \mathbb{I L}_{\nu}^{k}$ is a formal deformation of $\mathcal{L}_{\nu}$.
Remark 3. As mentioned in [2], if $\mathscr{L}_{\nu}$ is 1 -differentiable, so are all the $\mathbb{I L}_{\nu}^{k}{ }^{\prime} s$. In this case, we make use of $\tau$ only on $\mu^{*} \Lambda^{2}(M)$, where it is uniquely defined by $\mu^{*} \circ \tau=\mathrm{id}$. Thus thm. 2. holds true for 1 -differentiable deformations without the assumption that $M$ admits a $\mathbb{G}$-invariant connection. As in [2], it follows that every $\mathbb{G}$-invariant 1 -differentiable deformation of order $k$ extends to a $\mathbb{G}$-invariant 1 -differentiable deformation.

## INVARIANT DIFFERENTIAL DEFORMATIONS WITH DRIVER $\mathbf{P}+\nu \mathbf{r} \mathbf{S}_{\Gamma}^{3}$

The coefficient of $\nu$ in a differential deformation of $P$ is a cocycle of $A_{\text {loc }, n c}^{1}(N)$, thus it has the form $C=r S_{\Gamma}^{3}+\mu^{*} \Omega+\partial E$. A basic step in contructing a differential deformation equal to $P+\nu C$ at the order 1 is to obtain a differential deformation equal to $P+\nu r S_{\Gamma}^{3}$ at the order 1. Its existence is granted by thm. 3.3. of [2] and what we are going to prove now is that, if $\Gamma$ is invariant, the differential deformation constructed in [2] is also invariant.

THEOREM 4. Assume that $M$ admits a $\mathbb{G}$-invariant linear connection. Then, given $r \in \mathbb{R}_{0}$, there exists a unique differential deformation $\mathcal{L}_{\nu}$ of $P$ with driver $P+$ $+\nu r S_{\Gamma}^{3}$, such that

$$
\begin{equation*}
\partial_{\nu} \theta+\mathbb{L}_{\nu}^{1}\left(\mathcal{L}_{\nu}, F\right)=0 \tag{1}
\end{equation*}
$$

where $\mathbb{L}_{\nu}^{1}\left(\mathcal{L}_{\nu}, F\right)$ is defined as in thm. 2 for $\Omega=F$ and $\theta$ is the map

$$
\Sigma \nu^{k} u_{k} \rightarrow \Sigma(2 k-1) \nu^{k} u_{k}
$$

Moreover, this $\mathcal{L}_{\nu}$ is $\mathbb{G}$-invariant.
The result is proved in [2], thm. 3.3, except the invariance of $\mathscr{L}_{\nu}=\Sigma \nu^{k} C_{k}$. We will prove by induction on $k$ that $C_{k}$ is invariant. It is true for $k=0,1$. As in [2], $\xi$ is defined on a contractible open subset $U$ by $\left.F\right|_{U}=\operatorname{di}(\xi) F$.

Recall that a 2 -cocycle $C$ has a unique decomposition $C=r^{\prime} S_{\Gamma}^{3}+\mu^{*} D$, where $D$ is a cocycle; thus $C=\mu^{*} \hat{C}$, where $\hat{C}=r^{\prime}\left\langle\Lambda, \phi_{\Gamma}\right\rangle+D$. The cocycle $D$ is not unique but, whatever it is, $\mu^{*} i(\xi) \partial^{\prime} \hat{C}=-r^{\prime} S_{\Gamma}^{3}$. Thus $p C+\mu^{*} i(\xi) \partial^{\prime} \hat{C}=0$ implies $C=0$ provided $p \neq 0$ and 1 .

Consider now $C_{k}$. The relation (1) implies that

$$
L_{\xi} C_{k}+(2 k+1) C_{k}-\partial \mu^{*} i(\xi) \tau C_{k}=\sum_{\substack{p+q=k \\ p, q>0}}\left[C_{p}, \mu^{\left.* i(\xi) \tau C_{q}\right]}\right.
$$

and standard computations (see [2], lemma 3.1) reduce this equality to

$$
(2 k-1) C_{k}+\mu^{*} i(\xi) \partial^{\prime} \tau C_{k}=\sum_{\substack{p+q=k \\ p, q>0}}\left[C_{p}, \mu^{*} i(\xi) \tau C_{q}\right] .
$$

Apply $L_{X}(X \in \mathbb{G})$ to both sides. If $X=H_{u}$ on $U, L_{X} \xi=H_{u-L} \xi^{u}$. We thus obtain, assuming that $C_{p}$ is invariant for $p<k$,

$$
\begin{equation*}
(2 k-1) L_{X} C_{k}+\mu^{*} i(\xi) \partial L_{X} \tau C_{k}=-\frac{1}{2} i\left(u-L_{\xi} u\right)\left[\mathcal{L}_{\nu}, \mathcal{L}_{\nu}\right]_{k}=0 \tag{2}
\end{equation*}
$$

On the other hand, $\partial C_{k}$ is invariant. Thus, by [3], prop.8.1.

$$
C_{k}=f S_{\Gamma}^{3}+\mu^{*} \Omega+E+\partial E^{\prime}
$$

where $E, \mathrm{~d} f$ and $\mathrm{d} \Omega$ are invariant. Then

$$
\tau C_{k}=f\left\langle\Lambda, \phi_{\Gamma}\right\rangle+\Omega+\tau E+\tau \partial E^{\prime}
$$

where $\tau E$ is invariant and $\tau \partial E^{\prime}$ is a coboundary and

$$
\mu^{*} L_{X} \tau C_{k}=L_{X} f \cdot S_{\Gamma}^{3}+\mu^{*}\left(L_{X} \Omega+L_{X} \tau \partial E^{\prime}\right)
$$

where $L_{X} f$ is constant and $L_{X}\left(\Omega+\tau \partial E^{\prime}\right)$ is a cocycle.
Since $2 k-1>1$, (2) implies that $L_{X} C_{k}=0$. Hence the result.

## THE GENERAL CASE

THEOREM 5. Let $M$ admit a $\mathbb{G}$-invariant linear connection. Then every invariant formal deformation of $P$ of any order is the driver of an invariant deformation of $P$.

We refer to the proof of thm. 3.4 of [2] and observe that every invariant 2 -cocycle can be written $r S_{\Gamma}^{3}+\mu^{*} \eta+\partial T$, where $\eta$ and $T$ are invariant. The proof is then entirely similar to the above-mentioned one, using thm. 2 and 4.

## STAR-PRODUCTS

A differential weak star-product (resp. star-product) of order $k$ is a series $M_{\lambda}=\Sigma \lambda^{i} C_{i}$ of differential bilinear maps $C_{i}: N \times N \rightarrow N$ symmetric (resp. and $n c$ ) for $i$ even $\geqslant 2$, antisymmetric and $n c$ for $i$ odd, such that $C_{0}=\mathrm{m}:(u, v) \rightarrow u v$, $C_{1}=P$ and such that $M_{\lambda}$ is associative up to the order $k$.

It is shown in [6], $\S 5$ that if $M_{\lambda}$ is a weak star-product of order $k$, its terms
$C_{2 i}(2 i<k)$ take the form $C_{2 i}=\bar{C}_{2 i}+a_{i} \mathbf{m}$ with $a_{i} \in \mathbb{R}$ and $\bar{C}_{i} n c$. Denote by $\mathbb{P}_{\lambda}$ the set of all formal series $1+\sum_{i=1}^{\infty} a_{i} \lambda^{i}\left(a_{i} \in \mathbb{R}\right)$. It is then easily seen that each weak star-product $M_{\lambda}$ can be factorized in a unique way

$$
\begin{equation*}
M_{\lambda}=p\left(\lambda^{2}\right) \bar{M}_{\lambda} \tag{3}
\end{equation*}
$$

where $p(\lambda) \in \mathbb{P}_{\lambda}$ and $\bar{M}_{\lambda}$ is a star-product.
From each weak star-product (resp. of order $2 k$ ) $M_{\lambda}$ derives a formal deformation of $P$ (resp. of order $k-1$ )

$$
\mathcal{L}_{\nu}^{M}(u, v)=\frac{1}{2 v}\left[M_{\lambda}(u, \nu)-M_{\lambda}(v, u)\right]_{\lambda=\nu^{2}}
$$

Conversely, a formal deformation $\mathcal{L}_{\nu}=\Sigma \nu^{i} C_{2 i+1}$ derives from a (unique) week star-product if and only if

$$
C_{3}=\frac{1}{3!} S_{\Gamma}^{3}+\mu * \Omega+\partial E
$$

where $\mathrm{d} \Omega=0$ ([4], thm. 3.5).
It follows from (3) that, if $\mathcal{L}_{\nu}$ derives from $M_{\lambda}, M_{\lambda}$ is a star product if and only if $\mathcal{L}_{\nu}$ has no divisor in $\mathbb{P}_{\nu} \backslash\{1\}$.

The existence of invariant star-products is now ruled by the following theorem. The case of weak star-products is easily deduced by (3).

THEOREM 6. Assume that $M$ admits a $\mathbb{G}$-invariant linear connection $\Gamma$. Then every invariant differential star-product of order $2 k$ is the driver of order $2 k$ of an invariant star-product. In particular, $M$ admits at least one invariant star--product.

Let $M_{\lambda}^{k}=\sum_{i=0}^{2 k} \lambda^{i} C_{i}$ be an invariant differential star-product of order $2 k$.
Assume first that $k>1$. If $\mathcal{L}_{\nu}^{k-1}$ derived from $M_{\lambda}^{k}$, it is invariant and thus it extends to an invariant $\mathcal{L}_{\nu}$. This $\mathcal{L}_{\nu}$ derives from a weak star-product $M_{\lambda}=\sum_{i=0}^{\infty} \lambda^{i} C_{i}^{\prime}$. It is easily seen that $M_{\lambda}$ is differential. It is invariant. Indeed, with the notations of [4], if $X \in \mathbb{G}$

$$
0=L_{X}\left(M_{\lambda} \Delta M_{\lambda}\right)=2 M_{\lambda} \Delta L_{X} M_{\lambda}
$$

and $L_{X} M_{\lambda}=\sum_{i=1}^{\infty} \lambda^{2 i} L_{X} C_{2 i}^{\prime}$. Thus, by [4], cor. 3.7, $L_{X} M_{\lambda}=0$.
We have now to check if $M_{\lambda}$ extends $M_{\lambda}^{k}$.
If $i<k-1, C_{2 i}^{\prime}=C_{2 i}$. This is proved by induction on $i$ as follows. If it is
true for $j<k-2$, we have

$$
\begin{aligned}
& P \Delta\left(C_{2 j+2}-C_{2 j+2}^{\prime}\right)=0, \\
& \mathrm{~m} \Delta\left(C_{2 j+4}-C_{2 j+4}^{\prime}\right)+C_{2} \Delta\left(C_{2 j+2}-C_{2 j+2}^{\prime}\right)=0, \\
& P \Delta\left(C_{2 j+4}-C_{2 j+4}^{\prime}\right)+C_{3} \Delta\left(C_{2 j+2}-C_{2 j+2}^{\prime}\right)=0
\end{aligned}
$$

hence, by [4], lemma 3.6, $C_{2 j+2}=C_{2 j+2}^{\prime}$.
For $i=k-1$, we only have

$$
P \triangle\left(C_{2 k-2}-C_{2 k-2}^{\prime}\right)=0
$$

thus, by the same lemma,

$$
C_{2 k-2}=C_{2 k-2}^{\prime}+a \mathrm{~m}(a \in \mathbb{R})
$$

Replacing $M_{\lambda}$ by $\left(1-a \lambda^{2 k-2}\right) M_{\lambda}$, we obtain $C_{i}^{\prime}=C_{i}$ for $i \leqslant 2 k-2$, but now $C_{2 k-1}^{\prime}=C_{2 k-1}-a P$.

Define

$$
\pi: \Sigma \lambda^{k} u_{k} \rightarrow \Sigma k \lambda^{k} u_{k}
$$

Then $\operatorname{Ad}\left(\exp \lambda^{t} b \pi\right) M_{\lambda}$ is a new weak star-product equal to $M_{\lambda}$ up to the order $t$ and its term of order $t+1$ is $C_{t+1}^{\prime}+b P$. Thus replacing again $M_{\lambda}$ by $\operatorname{Ad}(\exp$ $\left.\lambda^{2 k} a \pi\right) M_{\lambda}$, we obtain a new $M_{\lambda}$ equal to $M_{\lambda}^{k}$ up to the order $2 k-1$ and still invariant.

For the term of order $2 k$, we have now

$$
\mathrm{m} \Delta\left(C_{2 k}^{\prime}-C_{2 k}\right)=0
$$

hence $C_{2 k}^{\prime}-C_{2 k}$ is a Hochschild 2-cocycle. Being symmetric, it is a coboundary. It is moreover invariant. By [6], it is of the type $m \triangle T$ for some invariant $T$. Transforming now $M_{\lambda}$ by Ad $\left(1+\lambda^{2 k} T\right)$, we finally obtain a weak star-product $M_{\lambda}$ equal to $M_{\lambda}^{k}$ up to the order $2 k$ and invariant. The related starproduct $\bar{M}_{\lambda}$ is still invariant and equal to $M_{\lambda}^{2 k}$ up to the order $2 k$, hence the result.

If $k=1$, according to [6], $M_{\lambda}^{1}=m+\lambda P+\frac{1}{2} \lambda\left(P_{\Gamma}^{2}+m \triangle T\right)$ where $T$ may be choosen invariant. Then $M_{\lambda}^{1}$ can be extended by $M_{\lambda}^{1}+\lambda^{3}\left(\frac{1}{3!} S_{\Gamma}^{3}+P \Delta T\right)$ and the argument developped for $k>1$ can be applied without changes.

If $k=0, \mathrm{~m}$ extends first by $\mathrm{m}+\lambda P+\frac{1}{2} \lambda^{2} P_{\Gamma}^{2}$.

## REFERENCES

[1] D. ARNAL, J.C. CORTET, P. MOLIN, G. Pinczon, Covariance and geometric invariance ın *-quantization, J. Math. Phys., 24, 2, 1983, pp. 276-283.
[2] M. De Wilde, P.B.A. Lecomte, Existence of star-products and of formal deformations of the Poisson Lie algebra of arbitrary symplectic manifolds, Lett. in Math. Phys., 7, 1983, pp. 487-496.
[3] M. De Wilde, P.B.A. Lecomte, D. Melotte, Invariant cohomology of the Poisson Lie algebra of a symplectic manifold, to appear.
[4] M. DE Wilde, P.B.A. Lecomte, Existence of star-products on exact manifolds, to appear in Ann. Inst. Fourier, 35, 2, 1985.
[5] S. GUTT, Déformations formelles de l'algèbre des fonctions différentiables sur une variété symplectique, Doctor thesis, Brussels 1979.
[6] A. Lichnerowicz, Déformations d'algèbres associées à une variété symplectique (les **--produits/, Ann. Inst. Fourier, 32, 1982, 157-209.
[7] A. Lichnerowicz, Sur les algèbres formelles associées par déformation à une variété symplectique, Ann. di Math., 123, 1980, 287 - 330.
[8] O.M. NEROSLAVSY, A.T. VLaSSOV, Existence de produits * sur une variété, C.R. Acad. Sc. Paris, I, 292, 1981, 71.
[9] J. VEY, Déformation du Crochet de Poisson d'une variété symplectique, Comm. Math. Helv., 50, 1975, 421-454.

Manuscript received: November 3, 1984.


[^0]:    Key Words: Symplectic manifold, deformations of the Poisson Lie algebra, star-products, invariance.

    1980 Mathematics Subject Classification: 53 C 15.

